## Notice of References Cited Application/Control No. 10/578,235 Examiner LIN B. OLSEN Applicant(s)/Patent Under Reexamination LAVAREC, ERWANN Page 1 of 1

## U.S. PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Name	Classification
*	Α	US-3,381,456	05-1968	TAYLOR ROGER G	56/10.2A
*	В	US-5,284,522	02-1994	Kobayashi et al.	134/18
*	С	US-5,353,224	10-1994	Lee et al.	701/25
*	D	US-6,255,793	07-2001	Peless et al.	318/580
*	Е	US-6,615,108	09-2003	Peless et al.	700/245
*	F	US-2003/0102014	06-2003	Yoshino, Junji	134/21
*	G	US-2004/0193349	09-2004	Flann et al.	701/050
*	Н	US-2004/0211444	10-2004	Taylor et al.	134/018
*	I	US-2005/0038578	02-2005	McMurtry et al.	701/025
*	J	US-2005/0197757	09-2005	Flann et al.	701/050
*	K	US-2008/0039974	02-2008	Sandin et al.	700/258
*	L	US-2008/0065347	03-2008	Lavarec et al.	702/155
	М	US-			

## FOREIGN PATENT DOCUMENTS

*		Document Number Country Code-Number-Kind Code	Date MM-YYYY	Country	Name	Classification
	N	EP 490736 A2	06-1992	European Patent	LEE et al.	
	0	EP 1265119 A2	12-2002	European Patent	MORI et al.	
	Р	GB 1487360 A	09-1977	United Kingdom	KREMNITZ W	
	Ø					
	R					
	Ø					
	Т					

## **NON-PATENT DOCUMENTS**

*		Include as applicable: Author, Title Date, Publisher, Edition or Volume, Pertinent Pages)				
	U	Zack J. Butler, Alfred A Rizzi and Ralph L. Hollis, Contact Sensor-based Coverage of Rectilinear Environments, Proceedigs of 1999 IEEE Int. Symposium on Intelligent Control/Intelligent Systems and Semiotics, 1999, pgs 266 - 271				
	V	Sylvia C. Wong, Bruce MacDonald, A Topological Coverage Algorithm for Mobile Robots, Proc. 2003 IEEE/RSJ Intl. Conf. on Intelligent Robots and Systems, 2003, Pgs 1685-1690				
	w					
	х					

\*A copy of this reference is not being furnished with this Office action. (See MPEP § 707.05(a).) Dates in MM-YYYY format are publication dates. Classifications may be US or foreign.